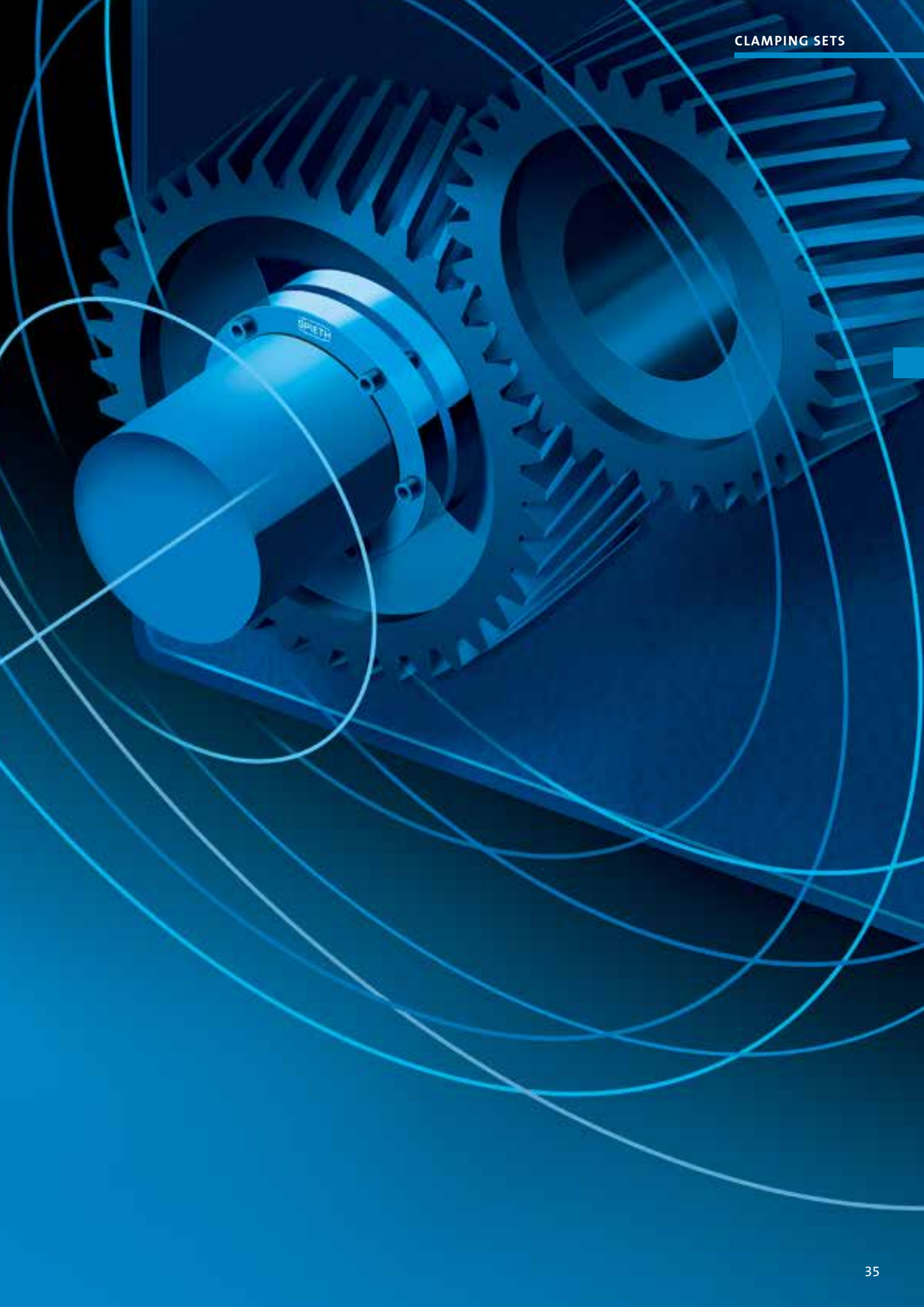


APPLYING ALL-ROUND PRESSURE WITH PRECISION

Spieth clamping sets – friction-locked shaft-hub connections.

Rising power densities. Increasing levels of dynamic stress. And the required function must be realised within increasingly restrictive cost parameters. The stringent demands of modern mechanical engineering can only be satisfied with high-quality shaft-hub connecting elements.

Spieth clamping sets apply uniform pressure. Without compromise. They are designed to be more accurate, precise, efficient, simpler to install and easier to service. The economical solution for modern machinery designs. Offering outstanding performance.



SPIETH CLAMPING SETS

4 UNIQUE FEATURES – NUMEROUS BENEFITS

Precise

All functional surfaces that determine precision are machined to the finest geometrical and positional tolerances.

Single-piece design

Unlike tapered clamping sets, the single-piece steel body does not have any joints that could compromise tolerances. This ensures that the high degree of precision achieved in the manufacturing process can also be brought to bear in the relevant application.

Self-centering

When subjected to axial compression, the unique geometry of the absolutely symmetrical base body ensures uniform transverse contraction in the direction of the shaft and hub. The resulting centring effect is equivalent to that of the hydro-expansion principle, only much simpler, safer and stiffer.

Intelligent

Cylindrical clamping sets exert very low levels of wear on their connecting components. Significantly better clamping homogeneity at the contact surfaces eliminates any possibility of peak clamping force acting at specific points, which frequently lead to damage and installation problems. At the same time, the Spieth design in the tensioned state is equivalent to the combination of a knee lever and a spring compressed against a block, thus guaranteeing an extremely rigid connection. And when released, the cylindrical clamping set easily returns to its original shape.

BENEFITS TO YOU

Competitiveness through technological leadership – a strategy that calls for an economical increase in power density, efficiency and accuracy. Cylindrical clamping sets create the foundation for this.

Lower Resource Input

- Simple configuration of connecting components.
- Simple installation and dismantling of all components thanks to mating play.
- Minimum axial drag during clamping process.
- Clamping force initiation can be freely configured.
- Quick-release connection.

More Success

- High level of concentricity.
- Minimised vibrational excitation.
- High torque levels and axial forces.
- Suitable for alternating torsion.
- Axial and angular position freely adjustable.
- Preserves connecting components.
- Connection can be automated/switched.
- Re-usable.

Series DSM .. 1, DSM .. 2



FIELDS OF APPLICATION

Spieth clamping sets are friction-locked shaft-hub connections for all areas of mechanical engineering. They are used wherever high-quality and reliable connections perform key functional roles. At the same time, they are the ideal solution for applications with high levels of replacement and adjustment as well as for manual or automated clamping of sleeves, skids, pivoting heads or rotary tables.

APPLICATION EXAMPLES

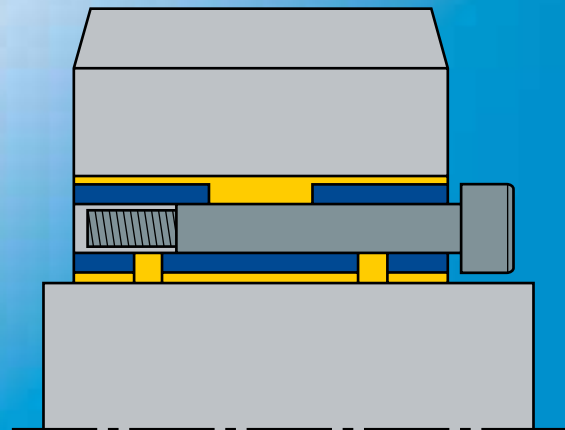
- In machining, forming and cutting machine tools.
- In handling and automation equipment.
- In materials handling.
- In general drive engineering and transmissions.
- In packaging machinery.
- In fixture construction.
- In compressors and pumps.
- In printing presses and paper-making technology.
- In textile machines.
- In woodworking machines.
- In process engineering applications for mixing, crushing and centrifuging.
- For metrology, control and test engineering.
- In precision engineering and optical technology.



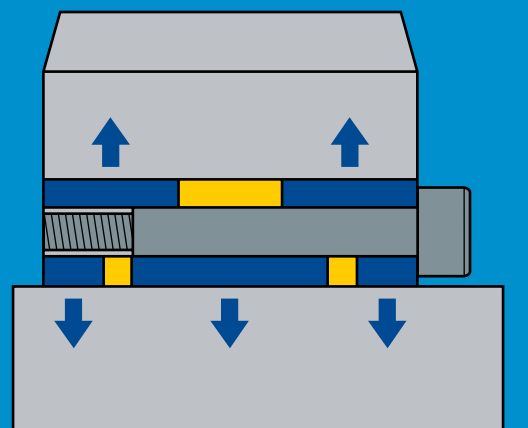
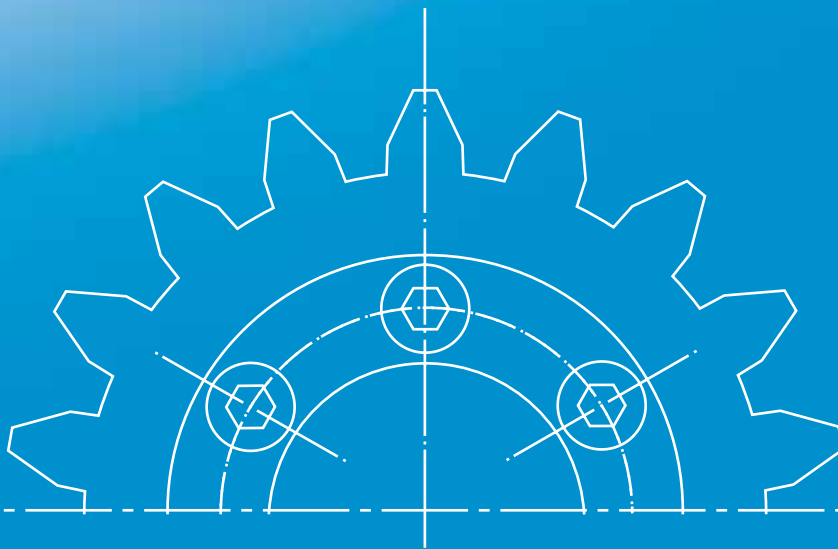
FUNCTIONAL PRINCIPLE

Shown here using a clamping set from series DSK with an integrated clamping screw.

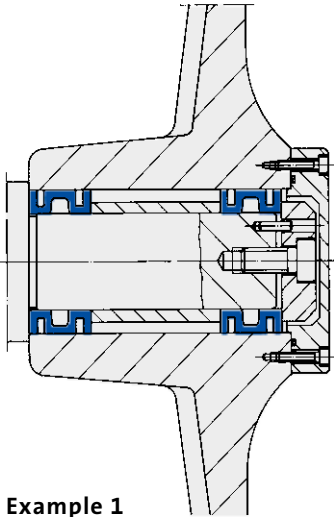
The principle is illustrated in a simplified diagram with enlarged play.



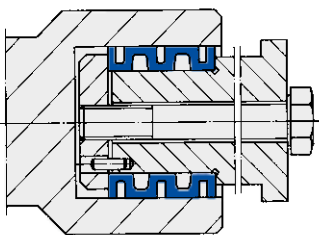
Clamping set released, easy installation or dismantling with mating play.



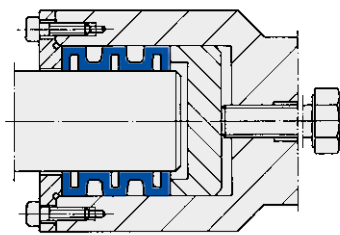
Clamping set clamped, connection is centred with a high load capacity. No lateral displacement during tightening. This ensures ultra-high precision centring and optimum concentricity.

**Example 1****Example 1: Blade wheel fixture**

The clamping sleeves arranged over a wide basis exert a positive influence on run-out accuracy and rotating flexural stress of the shaft-hub fit. The degree of torque which can be transferred with two consecutively arranged clamping sleeves is approx. 30 % higher than when using a single clamping sleeve.



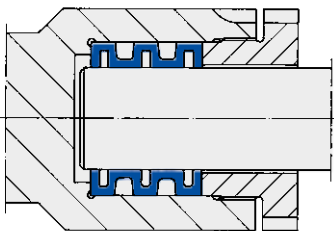
Example 2
Clamping force initiated
by tension screw.



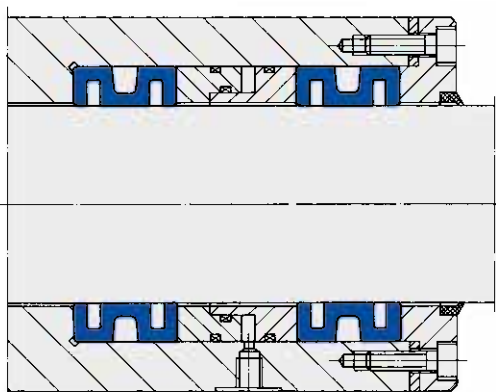
Example 3
Clamping force initiated
by set screw.

Example 2-4: Plug-in connections

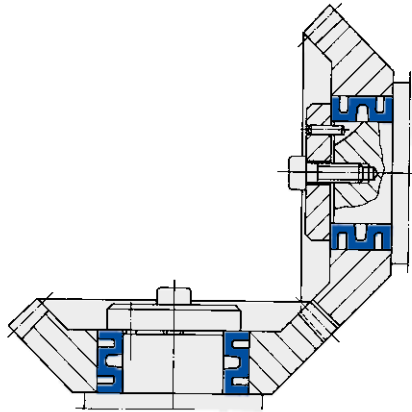
This shaft-hub connection is completely free of play and can be released an unlimited number of times. The tightening torque levels for clamping force initiating screws depend on the required clamping force for each individual clamping sleeve.



Example 4
Clamping force initiated
by hollow screw.

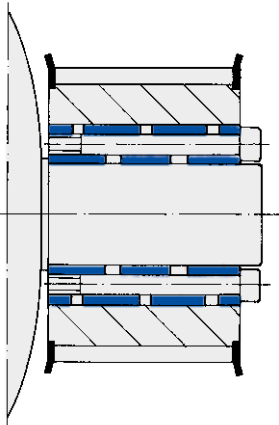
**Example 5****Example 5: Sleeve clamping**

The sleeve is hydraulically tensioned and precisely centred. Free movement is immediately possible in the un-tensioned state. The axial thrust created during the clamping process with single arrangement of a clamping sleeve is theoretically balanced out in this case by forces working in opposition. In practice, however, in case of a freely located sleeve, allowance must be made for a slight residual thrust as it is not possible to create identical clamping conditions at the clamping sleeves.



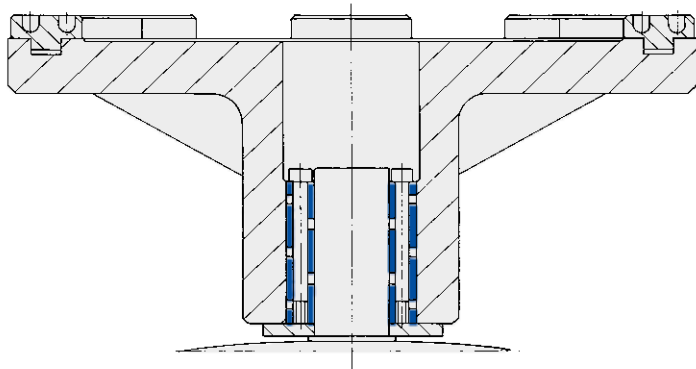
Example 6: Bevel wheel fixture

This connection is characterized by simple connecting components, a high degree of concentricity and absolute freedom from play.



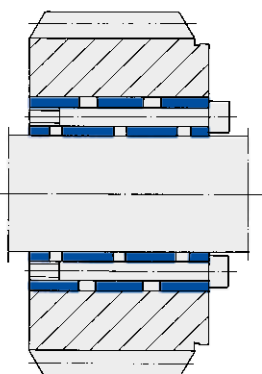
Example 7: Pulley fixture

The hub can be made of an aluminium alloy. Observe the minimum strength specification. High temperatures can impair retention force.



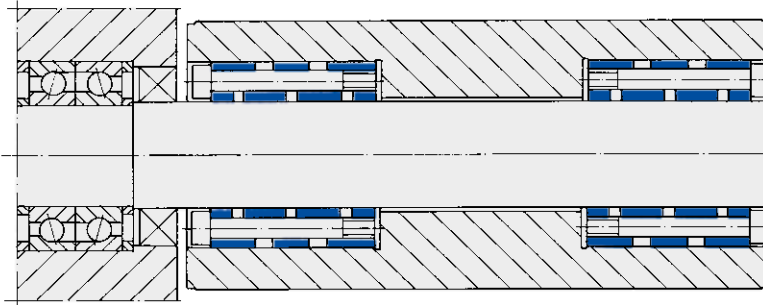
Example 8: Indexing plate

Indexing plate in alloy material at the shaft end of an indexing gear. Here, precise concentricity and run-out are vital.

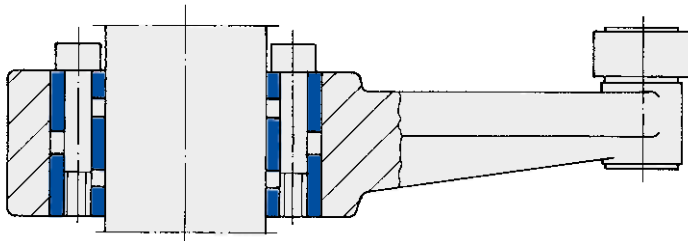


Example 9: Gear fixture

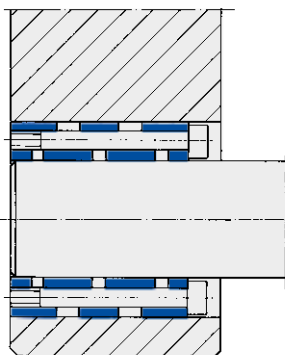
To satisfy the highest concentricity requirements, we recommend mounting a control facility on the gear to allow the concentricity to be checked and adjusted if necessary.

**Example 10: Pressure roller fixture**

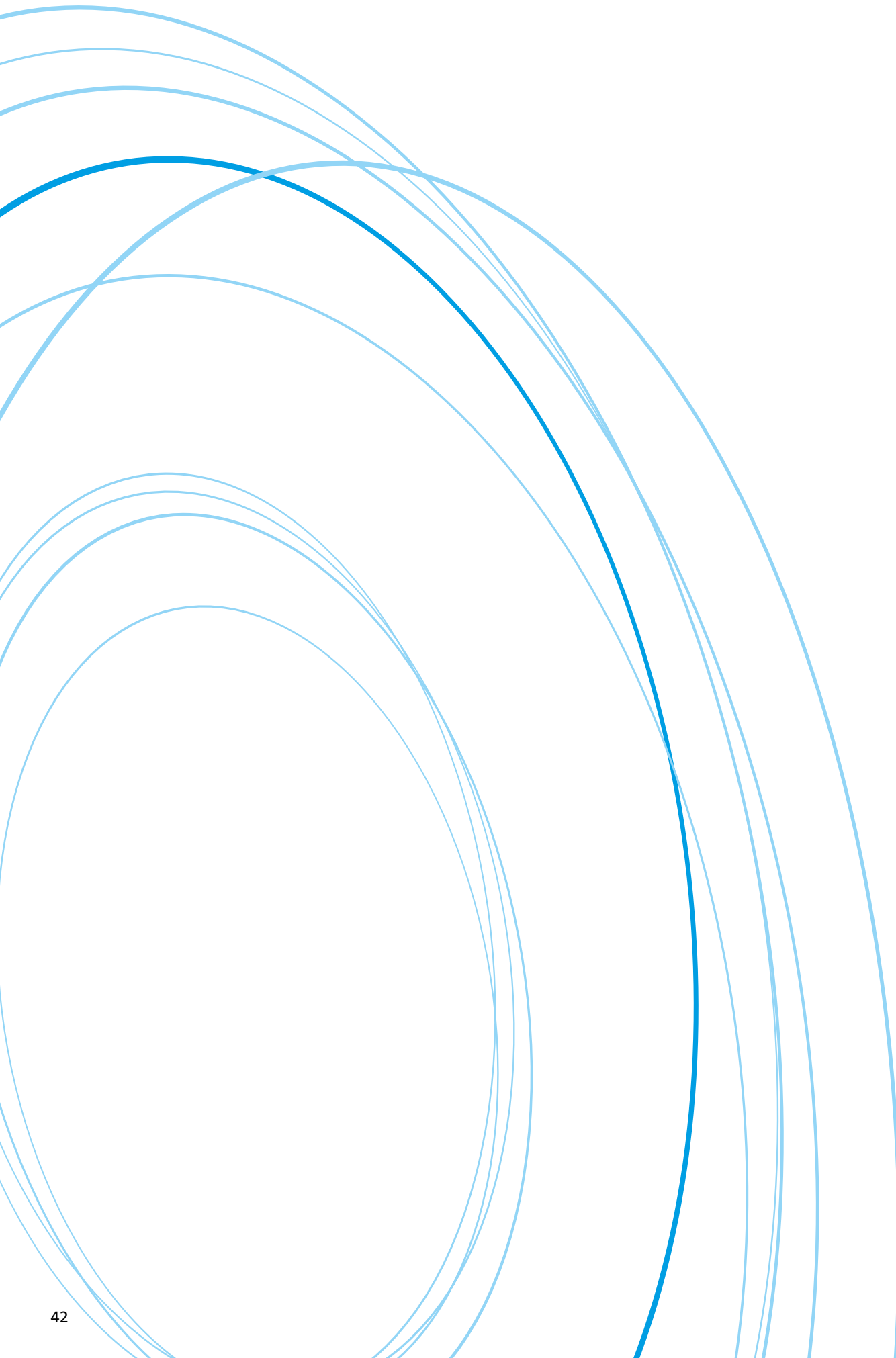
Here, 2 long clamping sets are used to achieve high overall radial rigidity due to intensive tensioning of the shaft and hub. The pressure roller is exchanged by pulling the shaft out of the bearings.

**Example 11: Rocker arm fixture**

The peripheral and axial position can be ideally adjusted during assembly.

**Example 12: Guide column**

Fixture of a guide column in the machine body.



SPIETH CLAMPING SETS: THE RIGHT CHOICE

We'll provide you with the perfect clamping sets for your application. We'll also help you choose the right one – with expert advice from our specialists.

Series DSK, DSL

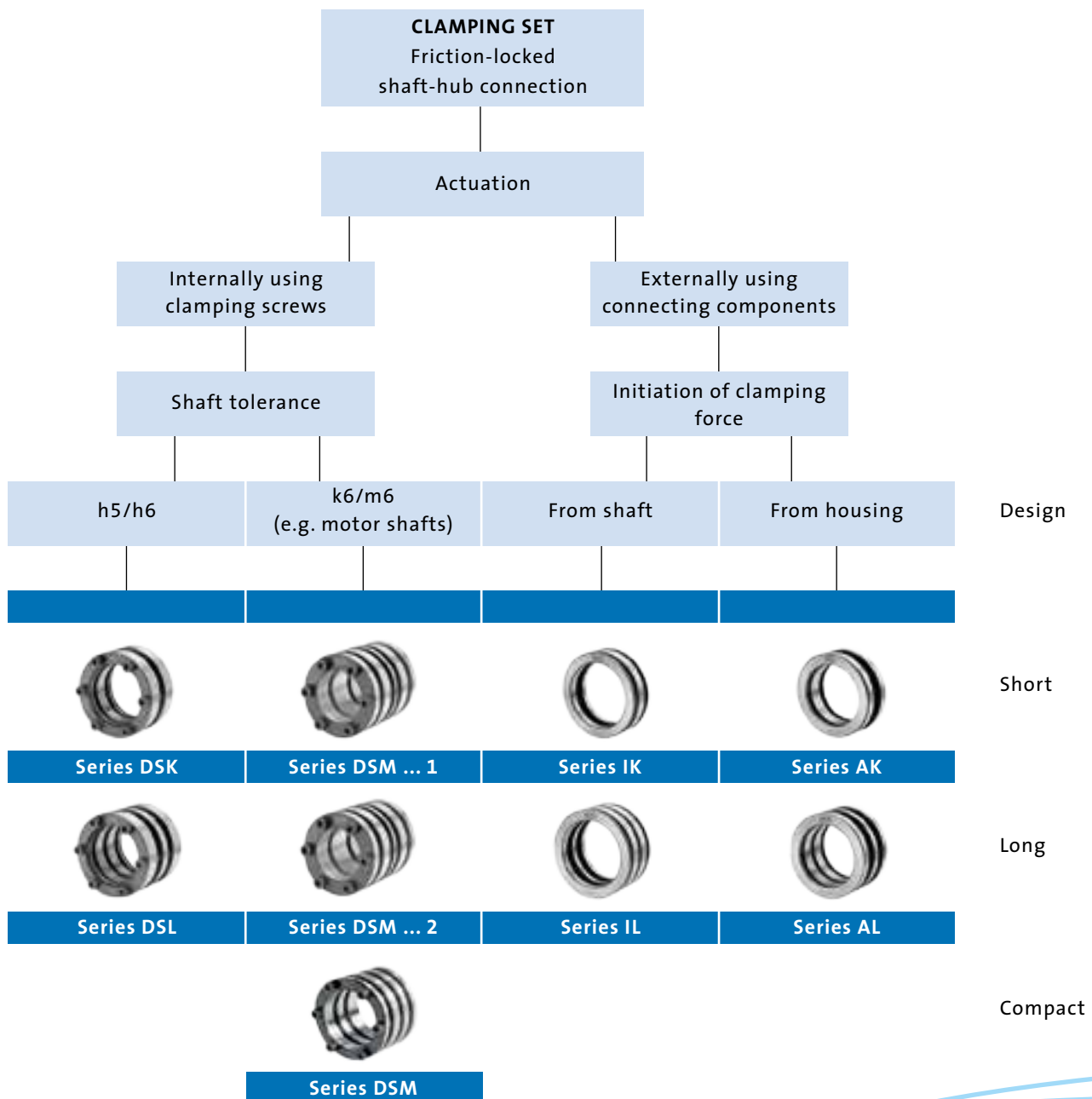
Ready-to-use friction-locked shaft-hub connection for quick and easy installation.

Series DSM

Ready-to-use friction-locked shaft-hub connection for use on motor shafts to DIN 748.

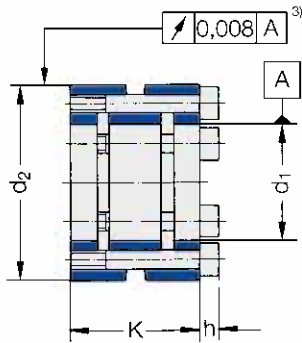
Series AK/IK and AL/IL

Friction-locked shaft-hub connection that can be automated. Clamping force initiation can be freely configured.



SPIETH CLAMPING SETS SERIES DSK

For shafts with h tolerance zone



Increased Transmissible Torques

Name	Dimensions in mm			Clamping screws				Transmittable forces		Moment of inertia J
	d ₁	d ₂	K	ISO 4762	h	M _A	No.	M	F _a	
	H6	h5			mm	Nm		Nm	N	kg cm ²
DSK 14.26	14	26	21	M3	3	2	6	40	5700	0.045
DSK 15.28	15	28	21	M3	3	2	6	44	5900	0.059
DSK 16.28	16	28	21	M3	3	2	6	45	5600	0.058
DSK 16.32	16	32	31	M4	4	5	6	100	12500	0.161
DSK 18.30	18	30	21	M3	3	2	6	53	5900	0.074
DSK 18.35	18	35	31	M4	4	5	6	110	12200	0.227
DSK 20.32	20	32	21	M3	3	2	6	64	6400	0.093
DSK 20.37	20	37	31	M4	4	5	6	130	13000	0.278
DSK 20.40	20	40	36	M5	5	7	6	180	18000	0.434
DSK 22.35	22	35	21	M3	3	2	6	76	6900	0.131
DSK 22.38	22	38	31	M4	4	5	6	160	14500	0.302
DSK 22.42	22	42	36	M5	5	10	6	330	30000	0.519
DSK 25.37	25	37	21	M3	3	2	6	94	7500	0.155
DSK 25.42	25	42	31	M4	4	5	6	220	17600	0.439
DSK 25.45	25	45	36	M5	5	10	6	388	31000	0.666
DSK 28.40	28	40	21	M3	3	2	6	113	8100	0.203
DSK 28.45	28	45	31	M4	4	5	6	280	20000	0.562
DSK 28.48	28	48	36	M5	5	10	6	450	32100	0.84
DSK 30.42	30	42	21	M3	3	2	6	126	8400	0.24
DSK 30.47	30	47	31	M4	4	5	6	321	21400	0.655
DSK 30.50	30	50	36	M5	5	10	6	510	34000	0.973
DSK 30.55	30	55	41	M6	6	13	6	588	39200	1.59
DSK 32.48	32	48	31	M4	4	5	6	360	22500	0.69
DSK 32.52	32	52	36	M5	5	10	6	585	36600	1.12
DSK 32.56	32	56	41	M6	6	13	6	634	39600	1.69
DSK 35.52	35	52	31	M4	4	5	6	390	22300	0.936
DSK 35.55	35	55	36	M5	5	10	6	679	38800	1.36
DSK 35.60	35	60	41	M6	6	17	6	935	53400	2.18
DSK 40.56	40	56	31	M4	4	5	6	430	21500	1.17
DSK 40.62	40	62	36	M5	5	10	6	835	41800	2.14
DSK 40.65	40	65	41	M6	6	17	6	1118	55900	2.9
DSK 40.70	40	70	52	M8	8	25	6	1270	63500	5.3
DSK 45.68	45	68	36	M5	5	10	6	987	43900	3.01
DSK 45.70	45	70	41	M6	6	17	6	1307	58100	3.76
DSK 45.75	45	75	52	M8	8	25	6	1485	66000	6.78
DSK 50.72	50	72	36	M5	5	10	6	1115	44600	3.6

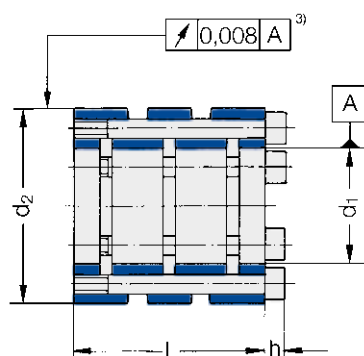
Name	Dimensions in mm			Clamping screws				Transmittable forces		Moment of inertia J
	d ₁	d ₂	K	ISO 4762	h	M _A	No.	M	F _a	
	H6	h5			mm	Nm		Nm	N	kg cm ²
DSK 50.75	50	75	41	M6	6	17	6	1500	60000	4.78
DSK 50.80	50	80	52	M8	8	35	6	1850	74000	8.52
DSK 55.80	55	80	41	M6	6	17	6	1693	61600	5.98
DSK 55.85	55	85	52	M8	8	35	6	2120	77100	10.5
DSK 60.85	60	85	41	M6	6	17	6	1885	62800	7.36
DSK 60.90	60	90	52	M8	8	35	6	2370	79000	12.9
DSK 65.90	65	90	41	M6	6	17	6	2072	63800	8.95
DSK 65.95	65	95	52	M8	8	35	6	2650	81500	15.5
DSK 70.100	70	100	52	M8	8	35	6	2990	85400	18.5
DSK 75.105	75	105	52	M8	8	35	6	3250	86700	21.9
DSK 80.110	80	110	52	M8	8	35	6	3520	88000	25.6
DSK 85.120	85	120	57	M8	8	35	6	3560	83800	40.3
DSK 90.120	90	120	52	M8	8	35	7	4300	95600	35.2
DSK 95.125	95	125	52	M8	8	35	8	4800	101100	40.7
DSK 100.130	100	130	52	M8	8	35	8	5050	101000	46.3
DSK 110.140	110	140	52	M8	8	32	10	6570	119500	60.2
DSK 120.150	120	150	52	M8	8	32	10	7170	119500	75.2
DSK 130.160	130	160	52	M8	8	32	10	7760	119400	92.5
DSK 140.170	140	170	52	M8	8	32	10	8360	119400	112
DSK 150.180	150	180	52	M8	8	32	10	8960	119500	134
DSK 160.190	160	190	52	M8	8	32	12	11470	143400	162
DSK 170.200	170	200	52	M8	8	32	12	12180	143300	190
DSK 180.210	180	210	52	M8	8	32	12	12900	143300	221
DSK 190.230	190	230	62	M10	10	60	12	18400	193700	487
DSK 200.240	200	240	62	M10	10	60	12	19300	193000	588
DSK 210.250	210	250	62	M10	10	60	12	20400	194300	614
DSK 220.260	220	260	62	M10	10	60	12	21600	196400	639
DSK 230.270	230	270	62	M10	10	60	12	22500	195700	812
DSK 240.280	240	280	62	M10	10	60	12	23600	196700	984
DSK 250.300	250	300	72	M10	10	60	15	32000	256000	1580
DSK 260.310	260	310	72	M10	10	60	15	33300	256200	1760
DSK 270.320	270	320	72	M10	10	60	15	34600	256300	1950
DSK 280.330	280	330	72	M10	10	60	15	36000	257100	2150
DSK 290.340	290	340	72	M10	10	60	15	36800	253800	2360
DSK 300.350	300	350	72	M10	10	60	15	38500	256700	2590

³⁾ d2 > 80 mm = Concentricity to IT4

All information is supplied without liability and subject to technical changes. Please observe the operating instructions at <https://www.spieth-maschinenelemente.de/en/download-faqs/catalogueinstructions/>

SPIETH CLAMPING SETS SERIES DSL

For shafts with h tolerance zone



Increased Transmissible Torques

Name	Dimensions in mm			Clamping screws				Transmittable forces		Moment of inertia J
	d ₁	d ₂	L	ISO 4762	h	M _A	No.	M	F _a	
	H6	h5			mm	Nm		Nm	N	kg cm ²
DSL 14.26	14	26	31	M3	3	2	6	60	8600	0.059
DSL 15.28	15	28	31	M3	3	2	6	66	8800	0.078
DSL 16.28	16	28	31	M3	3	2	6	73	9100	0.077
DSL 16.32	16	32	41	M4	4	5	6	187	23400	0.179
DSL 18.30	18	30	31	M3	3	2	6	87	9700	0.099
DSL 18.35	18	35	41	M4	4	5	6	205	22800	0.25
DSL 20.32	20	32	31	M3	3	2	6	100	10000	0.124
DSL 20.37	20	37	41	M4	4	5	6	230	23000	0.307
DSL 20.40	20	40	52	M5	5	7	6	250	25000	0.547
DSL 22.35	22	35	31	M3	3	2	6	110	10000	0.173
DSL 22.38	22	38	41	M4	4	5	6	275	25000	0.334
DSL 22.42	22	42	52	M5	5	10	6	485	44100	0.653
DSL 25.37	25	37	31	M3	3	2	6	140	11200	0.206
DSL 25.42	25	42	41	M4	4	5	6	348	27800	0.484
DSL 25.45	25	45	52	M5	5	10	6	566	45300	0.839
DSL 28.40	28	40	31	M3	3	2	6	160	11400	0.269
DSL 28.45	28	45	41	M4	4	5	6	420	30000	0.619
DSL 28.48	28	48	52	M5	5	10	6	653	46600	1.06
DSL 30.42	30	42	31	M3	3	2	6	180	12000	0.318
DSL 30.47	30	47	41	M4	4	5	6	470	31300	0.722
DSL 30.50	30	50	52	M5	5	10	6	705	47000	1.23
DSL 30.55	30	55	62	M6	6	13	6	717	47800	2.13
DSL 32.48	32	48	41	M4	4	5	6	520	32500	0.764
DSL 32.52	32	52	52	M5	5	10	6	760	47500	1.41
DSL 32.56	32	56	62	M6	6	13	6	770	48100	2.26
DSL 35.52	35	52	41	M4	4	5	6	600	34300	1.03
DSL 35.55	35	55	52	M5	5	10	6	871	49800	1.72
DSL 35.60	35	60	62	M6	6	17	6	1149	65700	2.91
DSL 40.62	40	62	52	M5	5	10	6	1040	52000	1.3
DSL 40.56	40	56	41	M4	4	5	6	690	34500	2.69
DSL 40.65	40	65	62	M6	6	17	6	1372	68600	3.87
DSL 40.70	40	70	77	M8	8	25	6	1420	71000	6.89
DSL 45.68	45	68	52	M5	5	10	6	1232	54800	3.77
DSL 45.70	45	70	62	M6	6	17	6	1607	71400	5.03
DSL 45.75	45	75	77	M8	8	25	6	1666	74000	8.81
DSL 50.72	50	72	52	M5	5	10	6	1412	56500	4.52

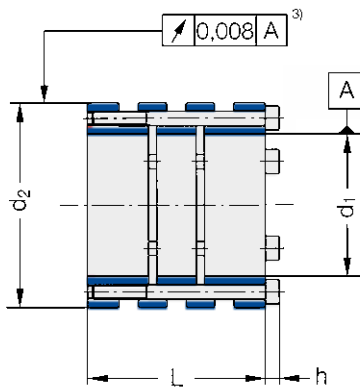
Name	Dimensions in mm			Clamping screws				Transmittable forces		Moment of inertia J
	d ₁	d ₂	L	ISO 4762	h	M _A	No.	M	F _a	
	H6	h5			mm	Nm		Nm	N	kg cm ²
DSL 50.75	50	75	62	M6	6	17	6	1851	74000	6.4
DSL 50.80	50	80	77	M8	8	35	6	2043	81700	11.1
DSL 55.80	55	80	62	M6	6	17	6	2103	76500	8
DSL 55.85	55	85	77	M8	8	35	6	2344	85200	13.7
DSL 60.85	60	85	62	M6	6	17	6	2359	78600	9.85
DSL 60.90	60	90	77	M8	8	35	6	2650	88300	16.7
DSL 65.90	65	90	62	M6	6	17	6	2617	80500	12
DSL 65.95	65	95	77	M8	8	35	6	2970	91400	20.1
DSL 70.100	70	100	77	M8	8	35	6	3288	93900	24
DSL 75.105	75	105	77	M8	8	35	6	3605	96100	28.4
DSL 80.110	80	110	77	M8	8	35	6	3919	98000	33.2
DSL 85.120	85	120	92	M8	8	35	6	3950	92900	60.2
DSL 90.120	90	120	77	M8	8	35	7	6850	152200	48.1
DSL 95.125	95	125	77	M8	8	35	8	7390	155600	55.7
DSL 100.130	100	130	77	M8	8	35	8	7780	155600	63.3
DSL 110.140	110	140	77	M8	8	32	10	10690	194400	82.3
DSL 120.150	120	150	77	M8	8	32	10	11670	194500	103
DSL 130.160	130	160	77	M8	8	32	10	12640	194500	126
DSL 140.170	140	170	77	M8	8	32	10	13610	194400	153
DSL 150.180	150	180	77	M8	8	32	10	14580	194400	184
DSL 160.190	160	190	77	M8	8	32	12	18670	233400	221
DSL 170.200	170	200	77	M8	8	32	12	19830	233300	260
DSL 180.210	180	210	77	M8	8	32	12	21000	233300	302
DSL 190.230	190	230	92	M10	10	60	12	27200	286300	678
DSL 200.240	200	240	92	M10	10	60	12	28540	285400	777
DSL 210.250	210	250	92	M10	10	60	12	29960	285300	885
DSL 220.260	220	260	92	M10	10	60	12	31390	285400	1000
DSL 230.270	230	270	92	M10	10	60	12	33000	287000	1130
DSL 240.280	240	280	92	M10	10	60	12	34250	285400	1270
DSL 250.300	250	300	102	M10	10	60	15	46300	370400	2050
DSL 260.310	260	310	102	M10	10	60	15	48000	369200	2280
DSL 270.320	270	320	102	M10	10	60	15	50200	371900	2520
DSL 280.330	280	330	102	M10	10	60	15	52800	377100	2780
DSL 290.340	290	340	102	M10	10	60	15	54200	373800	3060
DSL 300.350	300	350	102	M10	10	60	15	55800	372000	3360

³⁾ d₂ > 80 mm = Concentricity to IT4

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SPIETH CLAMPING SETS SERIES DSM

For motor shafts to DIN 748 with k6/m6 tolerance zone



Increased Transmissible Torques

Name	Dimensions in mm			Clamping screws				Transmittable forces		Moment of inertia J
	d ₁	d ₂	L	ISO 4762	h	M _A	No.	M	F _a	
		h5			mm	Nm		Nm	N	kg cm ²
DSM 14.2	14	26	26	M3	3	2	4	50	7100	0.055
DSM 16.28	16	28	26	M3	3	2	6	70	8800	0.071
DSM 16.1	16	32	26	M4	4	5	6	100	12500	0.138
DSM 16.2	16	32	36	M4	4	5	6	195	24400	0.178
DSM 18.30	18	30	26	M3	3	2	6	92	10200	0.091
DSM 18.2	18	34	36	M4	4	5	6	224	24900	0.222
DSM 19.32	19	32	26	M3	3	2	6	100	10500	0.118
DSM 19.1	19	35	26	M4	4	5	6	135	14200	0.192
DSM 19.2	19	35	36	M4	4	5	6	243	25600	0.247
DSM 20.32	20	32	26	M3	3	2	6	109	10900	0.115
DSM 20.1	20	40	36	M5	5	10	5	215	21500	0.437
DSM 20.2	20	40	46	M5	5	10	5	386	38600	0.534
DSM 22.35	22	35	26	M3	3	2	6	123	11200	0.162
DSM 22.1	22	42	36	M5	5	10	5	256	23300	0.524
DSM 22.2	22	42	46	M5	5	10	5	445	40500	0.639
DSM 24.36	24	36	26	M3	3	2	6	153	12800	0.174
DSM 24.1	24	44	36	M5	5	10	5	299	24900	0.621
DSM 24.2	24	44	46	M5	5	10	5	505	42100	0.757
DSM 25.37	25	37	26	M3	3	2	6	184	14700	0.191
DSM 25.1	25	45	41	M5	5	10	6	390	31200	0.755
DSM 25.2	25	45	52	M5	5	10	6	622	49800	0.925
DSM 28.40	28	40	26	M3	3	2	6	205	14600	0.251
DSM 28.1	28	48	41	M5	5	10	6	455	32500	0.954
DSM 28.2	28	48	52	M5	5	10	6	724	51700	1.17
DSM 30.42	30	42	26	M3	3	2	6	223	14900	0.297
DSM 30.1	30	52	57	M6	6	17	5	900	60000	1.85
DSM 30.2	30	52	62	M6	6	17	5	950	63300	1.92
DSM 32.48	32	48	36	M4	4	5	6	570	35600	0.754
DSM 32.1	32	55	57	M6	6	17	5	1000	62500	2.29
DSM 32.2	32	55	62	M6	6	17	5	1050	65600	2.37
DSM 35.52	35	52	36	M4	4	5	6	670	38300	1.02
DSM 35.1	35	58	57	M6	6	17	6	1300	74300	2.79
DSM 35.2	35	58	62	M6	6	17	6	1320	75400	2.88
DSM 38.55	38	55	36	M4	4	5	6	750	39500	1.24
DSM 38.1	38	60	57	M6	6	17	6	1480	77900	3.08
DSM 38.2	38	60	62	M6	6	17	6	1510	79500	3.18

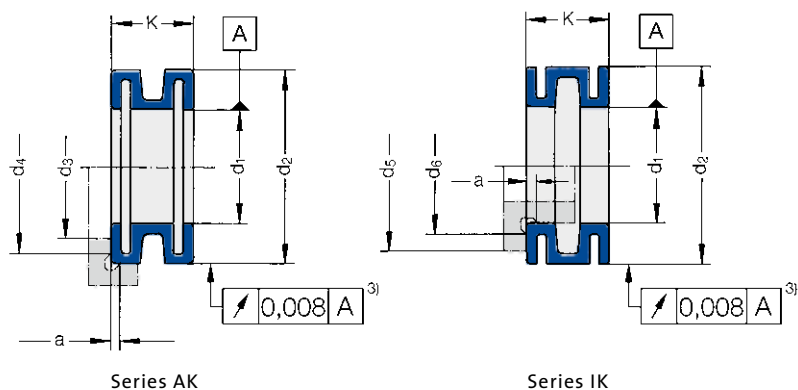
Name	Dimensions in mm			Clamping screws				Transmittable forces		Moment of inertia J
	d ₁	d ₂	L	ISO 4762	h	M _A	No.	M	F _a	
		h5			mm	Nm		Nm	N	kg cm ²
DSM 40.56	40	56	36	M4	4	5	6	805	40300	1.29
DSM 40.1	40	70	77	M8	8	40	5	1820	91000	7.8
DSM 40.2	40	70	92	M8	8	40	5	1854	92700	9.08
DSM 42.58	42	58	36	M4	4	5	6	850	40500	1.46
DSM 42.1	42	72	77	M8	8	40	5	1950	92900	8.63
DSM 42.2	42	72	92	M8	8	40	5	2000	95200	10
DSM 45.62	45	62	36	M4	4	5	6	920	40900	1.9
DSM 45.1	45	75	77	M8	8	40	5	2100	93300	10
DSM 45.2	45	75	92	M8	8	40	5	2250	100000	11.6
DSM 48.65	48	65	36	M4	4	5	6	980	40800	2.25
DSM 48.1	48	78	77	M8	8	40	5	2370	98800	11.5
DSM 48.2	48	78	92	M8	8	40	5	2600	108300	13.4
DSM 50.1	50	80	77	M8	8	40	6	2600	104000	12.6
DSM 50.2	50	80	92	M8	8	40	6	2700	108000	14.7
DSM 55.1	55	85	77	M8	8	40	6	3000	109100	15.6
DSM 55.2	55	85	92	M8	8	40	6	3100	112700	18.2
DSM 60.1	60	90	92	M8	8	40	6	3550	118300	22.3
DSM 60.2	60	90	122	M8	8	40	6	3550	118300	34.3
DSM 65.1	65	95	92	M8	8	40	6	4000	123100	26.9
DSM 65.2	65	95	122	M8	8	40	6	4000	123100	41.4
DSM 70.1	70	100	92	M8	8	40	6	4500	128600	30
DSM 70.2	70	100	122	M8	8	40	6	4500	128600	49.4
DSM 75.1	75	105	92	M8	8	40	7	5000	133300	38.1
DSM 75.2	75	105	122	M8	8	40	7	5000	133300	58.7
DSM 80.1	80	110	122	M8	8	40	8	6500	162500	69
DSM 85.1	85	115	122	M8	8	40	8	7150	168200	80

³⁾ d₂ > 80 mm = Concentricity to IT4

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SPIETH CLAMPING SLEEVES SERIES AK/IK

For shafts with h tolerance zone



Designation of a clamping sleeve with initiation of clamping force from the shaft with $d_1 = 28$ mm, $d_2 = 40$ mm and $K = 16$ mm: **IK 28.40**.

Order No.	Dimensions in mm			Initiation of clamping force		Transmittable forces		Dimensions for connecting components in mm					
	AK/IK	d_1 H6	d_2 h5	K	$F_{max}^{1)}$ N	$C_{min}^{2)}$ mm	M Nm	F_a N	d_3 max.	d_4 min.	d_5 min.	d_6 max.	a max.
8.12		8	12	12	10000	0.3	7	1750	9	10.8	11	9.2	1.5
10.15		10	15	12	11000	0.4	11	2200	11	13.8	14	11.2	1.5
12.18		12	18	12	11800	0.4	18	2950	13	16.8	17	13.2	1.5
14.20		14	20	12	13400	0.5	25	3620	15	18.8	19	15.2	1.5
15.22		15	22	12	13700	0.5	29	3840	16	20.8	21	16.2	1.5
16.22		16	22	12	14900	0.5	35	4320	17	20.8	21	17.2	1.5
18.25		18	25	12	15900	0.6	44	4930	19	23.8	24	19.2	1.5
20.32		20	32	16	20600	0.6	82	8240	24	30	28	22	1.7
22.35		22	35	16	21700	0.6	95	8680	27	33	30	24	1.7
25.37		25	37	16	24500	0.7	128	10290	29	35	33	27	1.7
28.40		28	40	16	26900	0.7	162	11570	32	38	36	30	1.7
30.42		30	42	16	28300	0.7	187	12450	34	40	38	32	1.7
32.48		32	48	21	32400	0.8	259	16200	40	46	40	34	2.2
35.52		35	52	21	34400	0.8	307	17540	43	50	44	37	2.2
40.56		40	56	21	38900	0.8	404	20230	48	54	49	42	2.2
45.68		45	68	26	44700	0.8	553	24590	58	65	55	48	3
50.72		50	72	26	49400	0.8	679	27170	62	69	60	53	3
55.80		55	80	31	59000	1.0	908	33040	70	77	65	58	3
60.85		60	85	31	63300	1.0	1082	36080	75	82	70	63	3
63.88		63	88	31	66000	1.0	1205	38280	78	85	73	66	3
65.90		65	90	31	67700	1.0	1298	39940	80	87	75	68	3
70.100		70	100	38	78800	1.0	1682	48070	88	96	82	74	4
75.105		75	105	38	83400	1.0	1907	50870	93	101	87	79	4
80.110		80	110	38	88100	1.1	2185	54620	98	106	92	84	4
85.115		85	115	38	92700	1.1	2442	57470	103	111	97	89	4
90.120		90	120	38	97200	1.1	2799	62200	108	116	102	94	4
95.125		95	125	38	101800	1.2	3139	66100	113	121	107	99	4
100.130		100	130	38	106500	1.3	3460	69200	118	126	112	104	4
110.140		110	140	38	115700	1.4	4136	75200	128	136	122	114	4
120.150		120	150	38	125000	1.4	4950	82500	138	146	132	124	4
125.155		125	155	38	129600	1.4	5343	85500	143	151	137	129	4
130.160		130	160	38	134300	1.5	5759	88 600	148	156	142	134	4
140.170		140	170	38	143500	1.5	6727	96100	158	166	152	144	4
150.180		150	180	38	152800	1.5	7672	102300	168	176	162	154	4

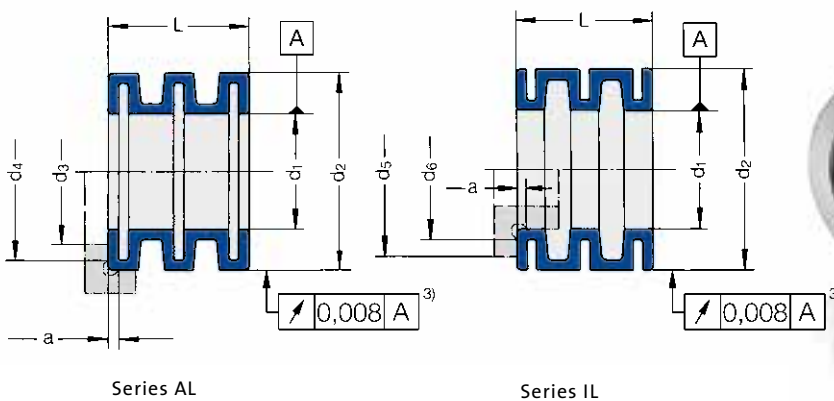
¹⁾ Max. perm. clamping force. For automated operation, the clamping sleeve should be clamped with max. 0.75x F .

²⁾ Design specification, not to be confused with actuation travel. For explanations, see p. 55.

³⁾ $d_2 > 80$ mm = Concentricity to IT4

SPIETH CLAMPING SLEEVES SERIES AL/IL

For shafts with h tolerance zone



Designation of a clamping sleeve with initiation of clamping force from the housing with $d_1 = 55$ mm, $d_2 = 80$ mm and $L = 52$ mm: **AL 55.80**.

Order No.	Dimensions in mm			Initiation of clamping force		Transmittable forces		Dimensions for connecting components in mm				
	d_1 H6	d_2 h5	L	$F_{max}^{1)}$ N	$C_{min}^{2)}$ mm	M Nm	F_a N	d_3 max.	d_4 min.	d_5 min.	d_6 max.	a max.
8.12	8	12	19	10000	0.5	12	3000	9	10.8	11	9.2	1.5
10.15	10	15	19	11000	0.6	21	4200	11	13.8	14	11.2	1.5
12.18	12	18	19	11800	0.7	35	5900	13	16.8	17	13.2	1.5
14.20	14	20	19	13400	0.8	49	6970	15	18.8	19	15.2	1.5
15.22	15	22	19	13700	0.8	54	7260	16	20.8	21	16.2	1.5
16.22	16	22	19	14900	0.8	64	8050	17	20.8	21	17.2	1.5
18.25	18	25	19	15900	0.9	80	8900	19	23.8	24	19.2	1.5
20.32	20	32	26	20600	0.9	124	12360	24	30	28	22	1.7
22.35	22	35	26	21700	0.9	143	13020	27	33	30	24	1.7
25.37	25	37	26	24500	1.1	190	15190	29	35	33	27	1.7
28.40	28	40	26	26900	1.1	237	16950	32	38	36	30	1.7
30.42	30	42	26	28300	1.1	272	18110	34	40	38	32	1.7
32.48	32	48	35	32400	1.2	389	24300	40	46	40	34	2.2
35.52	35	52	35	34400	1.2	457	26140	43	50	44	37	2.2
40.56	40	56	35	38900	1.2	599	29950	48	54	49	42	2.2
45.68	45	68	42	44700	1.2	804	35760	58	65	55	48	3
50.72	50	72	42	49400	1.2	988	39520	62	69	60	53	3
55.80	55	80	52	59000	1.5	1314	47790	70	77	65	58	3
60.85	60	85	52	63300	1.5	1557	51910	75	82	70	63	3
63.88	63	88	52	66000	1.5	1725	54780	78	85	73	66	3
65.90	65	90	52	67700	1.5	1848	56870	80	87	75	68	3
70.100	70	100	62	78800	1.5	2372	67770	88	96	82	74	4
75.105	75	105	62	83400	1.5	2690	71720	93	101	87	79	4
80.110	80	110	62	88100	1.6	3065	76650	98	106	92	84	4
85.115	85	115	62	92700	1.6	3427	80650	103	111	97	89	4
90.120	90	120	62	97200	1.6	3802	84500	108	116	102	94	4
95.125	95	125	62	101800	1.8	4251	89500	113	121	107	99	4
100.130	100	130	62	106500	2.0	4685	93700	118	126	112	104	4
110.140	110	140	62	115700	2.1	5599	101800	128	136	122	114	4
120.150	120	150	62	125000	2.1	6672	111200	138	146	132	124	4
125.155	125	155	62	129600	2.1	7206	115300	143	151	137	129	4
130.160	130	160	62	134300	2.2	7767	119500	148	156	142	134	4
140.170	140	170	62	143500	2.2	9037	129100	158	166	152	144	4
150.180	150	180	62	152800	2.2	10314	137520	168	176	162	154	4

¹⁾ Max. perm. clamping force. For automated operation, the clamping sleeve should be clamped with max. $0.75 \times F$.

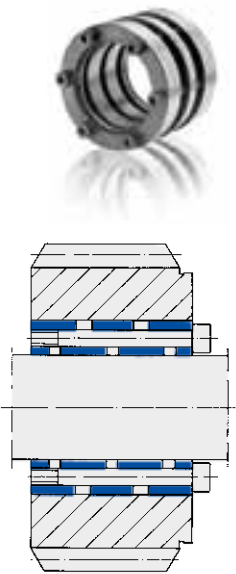
²⁾ Design specification, not to be confused with actuation travel. For explanations, see p. 55.

³⁾ $d_2 > 80$ mm = Concentricity to IT4

GENERAL APPLICATION

The clamping sleeve may only be actuated when the bore and outside surface of the clamping sleeve are covered by the connecting components. Otherwise the clamping set could be destroyed as a result of plastic deformation.

APPLICATION USING SCREWS



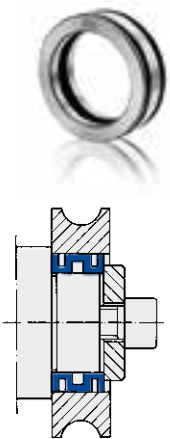
Assembly

1. Clean the clamping set, shaft and hub bore carefully and wet slightly with a low-viscosity machine oil.
2. Join the clamping set and connecting components without applying force.
3. Tighten the clamping screws evenly in diagonal order until the initial assembly play is eliminated. The play elimination phase is particularly important for ensuring good concentricity results.
4. Continue tightening evenly and gradually in diagonal sequence until you have applied full torque.
5. Finally, check the tightening torque all round.

Dismantling

1. Release the clamping screws gradually in diagonal sequence. Never completely unscrew one screw after the other. This would cause the last screw to be subjected to the total spring-back force exerted by the clamping sleeve and consequently to block. An attempt to release it can result in destruction of the hexagonal socket.
2. After releasing the clamp screws, all the components of the connection can be freely moved. After several assembly processes, an unfavourable alteration of the friction ratio between the head and contact surface of the clamping screws can take place. A stick-slip effect can occur during the tightening procedure, which results in jerky movement of the clamping screw. In this case, the contact surface of the screw head must be re-lubricated using a standard machine oil without additives.

APPLICATION WITHOUT SCREWS



Assembly

1. Clean the clamping sleeve, shaft and hub bore carefully and wet slightly with a low-viscosity machine oil.
2. Join the clamping sleeve and connecting components without applying force.
3. Initiate clamping force. The clamping sleeve deforms elastically and creates a friction-locked connection between the shaft and the housing bore.

Dismantling

1. Release the clamping force.
2. The clamping sleeve relaxes and resumes its original shape. All the parts are once again freely movable. Due to the many possible ways of initiating the clamping force, this description can only be formulated in general terms.

The clamping sets are manufactured from spring-hardened steel. The concentricity of the bore/outside diameter is accurate to 0.008 mm and from $d_2 > 80$ mm, concentricity to IT4.

The outside diameter is machined according to ISO tolerance h5. Depending on the design, the inside diameter is machined to ISO tolerance H6 or, for shaft ends, to DIN 748 (k6/m6).

Two different series (AK/AL and IK/IL) are offered to enable the different types of clamping force initiation. The AK/AL series sleeves are designed

for use where the clamping force is initiated from the housing (Fig. 1). IK/IL series clamping sleeves are used in cases where clamping force is initiated from the shaft (Fig. 2).

However, of decisive importance is that the clamping force is applied to the end faces of the clamping sleeves in the area of diameter d_3 and d_4 or d_5 and d_6 .

CONNECTING COMPONENTS

The cylindrical bore and outside surfaces of the clamping set must be completely covered by the connecting components. The shaft and bore must be machined cylindrically with a mean peak-to-valley height of $Rz=2.5 \dots 6.3$ μm microns.

To ensure that the stress exerted on the hub or housing bore remains within the elastic range, we recommend the following minimum wall thickness:

Steel C 45	$= 0.6 (d_2 - d_1)$
Aluminium alloys	
Minimum strength F 38	$= 1.0 (d_2 - d_1)$
Grey cast iron GG 25	
shrinkage-free casting	$= 1.0 (d_2 - d_1)$

Hub bore

The following manufacturing tolerance applies for all series:

H7 (H6 for stringent concentricity requirements or a hydraulically operated clamp).

Shaft

Shafts must generally be manufactured to manufacturing tolerance h5 (max. perm. h6). As an exception when the DSM series is used, shafts must be manufactured to DIN 748 for motor shafts (up to dia.50 mm in k6 tolerance field, from dia.55 mm in m6 tolerance field).

Series AK/IK, AL/IL (without screws)

To permit simple configuration of the connecting components, however, projection of the clamping sleeve up to max. a (Fig. 1 and 2) can be tolerated.

Initiation of clamping force

The functional surfaces of the connecting components, which are used to initiate clamping force in the clamping sleeves, must be manufactured with a run-out accuracy of 0.01 mm or to IT4.

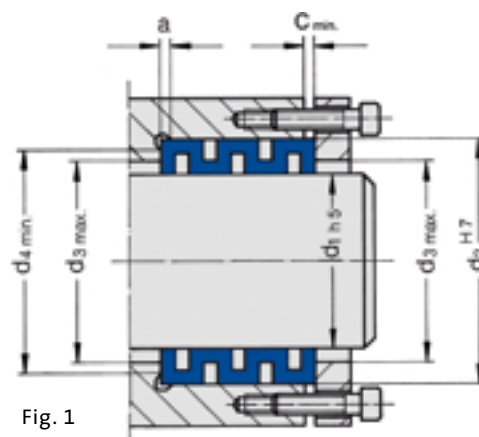


Fig. 1

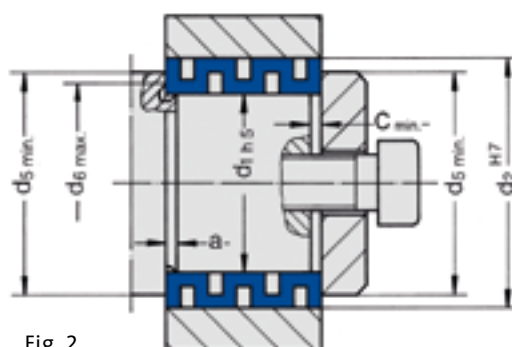


Fig. 2

CLAMPING SCREWS

Cheese-head screws with a hexagon socket ISO 4762 (DIN 912) with strength class 12.9 are used. As the power transmission of the clamping sleeves depends on the exerted

clamping force, the clamping screws should be tightened using a torque wrench.

M_A : Tightening torque per clamping screw

TRANSMITTABLE FORCES

DSK/DSL/AK/IK/AL/IL

The specifications provided in the table apply to a bore tolerance of H7 and a shaft tolerance of h5 in the connecting components. For an h6 shaft, in the most unfavourable scenario, a reduction of transmittable forces of approx. 10 % may be expected.

DSM

The specifications provided in the table apply to a bore tolerance of H7 and a shaft tolerance to DIN 748 (k6/m6).

M: Transmittable torque at $F_a = 0$

The specified values were ascertained in a series of tests, in which the connecting components were made of C45steel, produced with the stipulated surface quality.

The specified performance data are subject to the variation of the friction values of the different contact partners. The components are designed to be reusable, with frequent assembly and disassembly we recommend reducing the tightening torque. Please note that this can also reduce the transmissible torque.

F_a : Transmittable axial force at $M = 0$

The F_a values are calculated according to

$$F_a = 2000 \cdot \frac{M}{d_1} \text{ [N]}$$

Subjection of the clamped connection to steady, pulsating, alternating or sudden stress has no impact provided that the occurring peak forces do not exceed the catalogue values. The risk of fretting corrosion is always a possibility in friction-locked connections subjected to alternating torsion or rotating bending stress. This phenomenon can complicate dismantling, and can be prevented by complying with the following instructions:

$$\begin{aligned} \text{Perm. alternating torsion} & \quad \tilde{T}_{\text{perm.}} \leq 0,6 M \\ \text{Perm. rotating bending stress} & \quad \tilde{M}_{\text{bperm.}} \leq 0,3 M \end{aligned}$$

M and F_a :

If both torque and axial forces act on a clamping set at the same time, check using the following formula whether the resulting torque M_r is transmittable.

$$M \geq M_r = \sqrt{M_e^2 + \left(\frac{F_{ae} \cdot d_1}{2000}\right)^2} \text{ [Nm]}$$

- M = Transmittable torque (catalogue value) [Nm]
- M_e = Required torque [Nm]
- M_r = Resulting torque [Nm]
- F_{ae} = Required axial force [N]
- d_1 = Shaft diameter [mm]

For series AK/IK, AL/IL only**F: Maximum permissible clamping force**

To avoid the danger of fatigue failure and fretting corrosion, the clamping sleeves should be tensioned in case of high clamping/release cycle frequencies to a maximum of 0.75 F.

C: Required functional installation space

Spieth clamping sleeves must be clamped using the controlled application of force. The clamping force cannot be applied in relation to the clamping path. To prevent premature blocking, a "free" functional path "C" must be provided.

Automated operation

In the case of automated operation, for example, using hydraulic actuation, a variety of influencing variables can cause the actual values of the system to deviate from the catalogue values. For this application scenario, we strongly recommend that you verify the force or torque values required. In this application, care must be taken to ensure that the installation is completely free of axial play. To avoid fatigue failure and due to the danger of fretting corrosion, in case of high clamping/release cycle frequencies, the clamping sleeves should be tensioned at a maximum of 0.75x F.

General

If it is not possible to apply the clamping force F, the following formula is used for approximate determination of the torque M_{red} which can be transmitted with the given clamping force $F_{giv.}$ (<F).

$$M_{red} = \frac{M (F_{giv.} - 0.05 F)}{0.95 F} \text{ [Nm]}$$

To ascertain the necessary clamping force for a transmittable torque $M_{red} < M$ an approximation is possible using the following formula:

$$F_{req.} = \frac{M_{red} \cdot 0.95 F}{M} + 0.05 F \text{ [N]}$$

M = Transmittable torque
(catalogue value) [Nm]

M_{red} = Reduced transmittable
torque [Nm]

F = Max. perm. clamping force
(catalogue value) [N]

F_{ae} = Required axial force [N]

$F_{req.}$ = Required clamping force [N]

$F_{giv.}$ = Given clamping force (<F) [N]

NOTE

During the clamping process, the clamping sleeve reduces in length by some tenths of a mm (depending on the size of the clamping sleeve, the clamping force and the real dimensions of the clamping sleeve and connected components), dragging the clamped part in the direction of clamping. The resulting axial displacement of the clamped part can be up to 0.5 times the clamping path. When positioned against a thrust collar or similar, the axial thrust produces an intensive face contact with the clamped part. AK and IK series clamping sleeves can be supplied in a low-thrust ver-

sion. However, the retention force of these versions only achieves 0.5 times the values listed in the table.

For clamping sets with integrated clamping screws, this effect is theoretically cancelled as the actuating force is applied symmetrically. Due to the actual dimensions of all components, however, allowance must be made for a slight residual thrust in an undefined direction.